Baptiste CHATELIER^{‡,†,*}, Vincent CORLAY^{‡,*}, Matthieu CRUSSIERE^{†,*}, Luc LE MAGOAROU^{†,*}

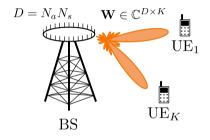
† Univ Rennes, INSA Rennes, CNRS, IETR-UMR 6164, Rennes, France
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baptiste.chatelier@insa-rennes.fr

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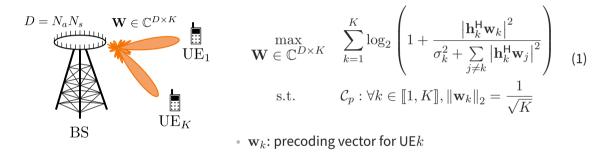




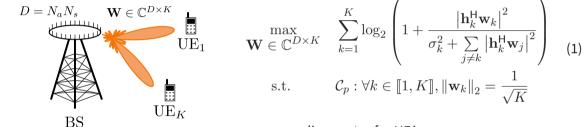


$$D = N_a N_s \quad \mathbf{W} \in \mathbb{C}^{D \times K} \quad \sum_{k=1}^{K} \log_2 \left(1 + \frac{|\mathbf{h}_k^{\mathsf{H}} \mathbf{w}_k|^2}{\sigma_k^2 + \sum_{j \neq k} |\mathbf{h}_k^{\mathsf{H}} \mathbf{w}_j|^2} \right) \quad (1)$$

$$\text{BS} \quad \mathbf{U} \mathbf{E}_K \quad \text{s.t.} \quad C_p : \forall k \in [\![1, K]\!], \|\mathbf{w}_k\|_2 = \frac{1}{\sqrt{K}}$$



• How to maximize the sum-rate with K parallel UEs in FDD mMIMO systems?

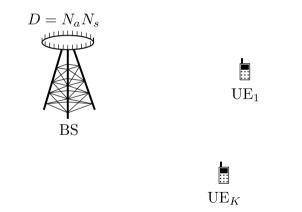


• \mathbf{w}_k : precoding vector for UEk

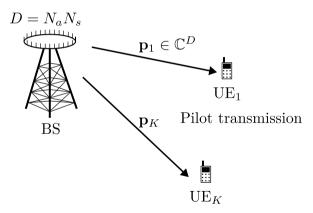
C_p: uniform power allocation policy

- Classical beamforming methods rely on the full CSI knowledge: $\mathbf{H} \in \mathbb{C}^{D imes K}$

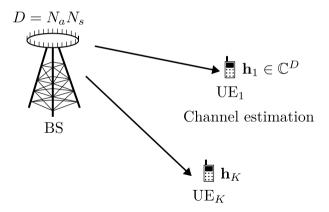
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- In FDD systems, how to minimize the CSI reporting overhead?



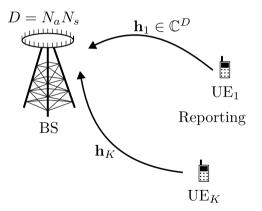
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Huge complexity reduction

TOWARDS TASK-BASED CSI COMPRESSION

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Is it possible to decode a beamforming matrix from the compressed CSI?

CONTRIBUTIONS

• Use of channel charting for task-based CSI compression

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- Learnable parameter optimization

Channel charting: dimensionality reduction method that preserves local neighborhoods

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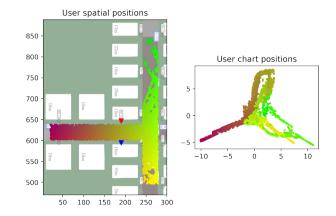
- Channel charting: dimensionality reduction method that preserves local neighborhoods
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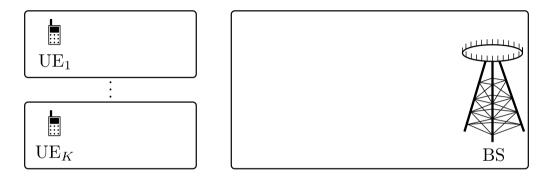
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$$\left\|\mathbf{x}_{i}-\mathbf{x}_{j}\right\|_{2}pprox\left\|\mathbf{z}_{i}-\mathbf{z}_{j}
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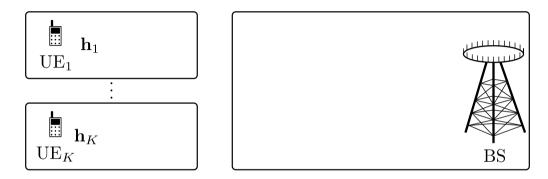
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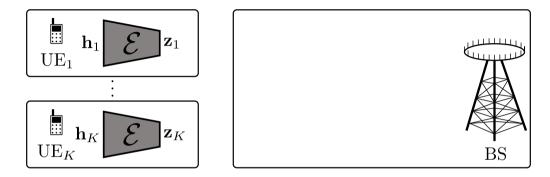




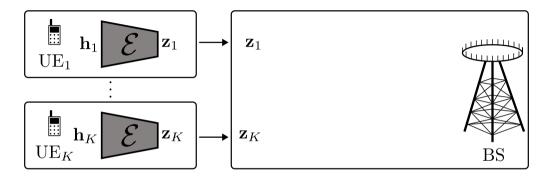
System model



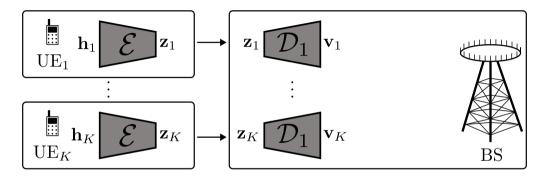
Downlink channel estimation



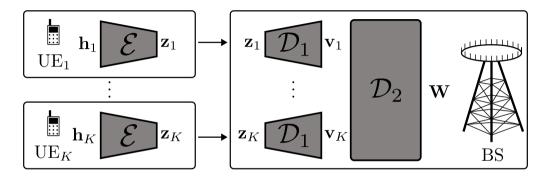
Channel compression



• Encoded channel transmission

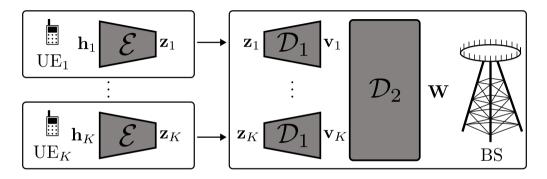


Individual decoding: mono-UE processing



• Parallel decoding: multi-UE processing

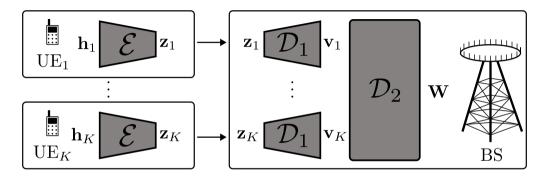
PROPOSED APPROACH



• Loss function: $\mathbf{v} = \left(\mathcal{D}_1 \circ \mathcal{E}\right)(\mathbf{h})$

$$\mathcal{L} = 1 - \frac{1}{|\mathcal{B}|} \sum_{\mathbf{h} \in \mathcal{B}} \frac{\left| \mathbf{v}^{\mathsf{H}} \mathbf{h} \right|^{2}}{\| \mathbf{h} \|_{2}^{2}}, \qquad (3)$$

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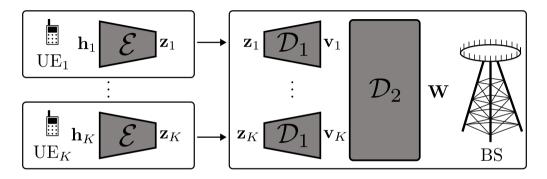


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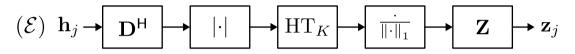
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- After denormalization, v is an imperfect channel estimate, that can be used in linear precoders

ENCODER ARCHITECTURE

• Architecture presented in^{1,2,3}



³Yassine, Chatelier, et al., "Model-Based Deep Learning for Beam Prediction Based on a Channel Chart".

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$$(\mathcal{E}) \quad \mathbf{h}_j \to \mathbf{D}^{\mathsf{H}} \longrightarrow [|\cdot|] \to \mathrm{HT}_K \to \underbrace{\overset{\cdot}{\|\cdot\|_1}} \to \mathbf{Z} \to \mathbf{z}_j$$

• $\mathbf{D} = \{\mathbf{h}_i\}_{i=1}^{N_c}$ and $\mathbf{Z} = \{\mathbf{z}_i\}_{i=1}^{N_c}$ are initialized through the ISOMAP algorithm

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• \mathbf{z}_j can be seen as a wisely chosen convex combination of calibration chart locations

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DECODER ARCHITECTURE

$$(\mathcal{D}_1) \quad \mathbf{z}_k \rightarrow \overrightarrow{\mathrm{RFF}} \stackrel{\mathbf{f}_k}{\longrightarrow} \overrightarrow{\mathrm{MLP}_{\mathbb{C},T}} \rightarrow \mathbf{v}_k$$
$$(\mathcal{D}_2) \quad \{\mathbf{v}_k\}_{k=1}^K \rightarrow \overrightarrow{\mathrm{concat.}} \rightarrow \overrightarrow{\mathrm{process.}} \rightarrow \mathbf{W}$$

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oncat. $\rightarrow \mathbb{P}$ process. $\rightarrow \mathbf{W}$

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$$\mathbf{f}_{k} = \begin{bmatrix} \cos\left(2\pi\mathbf{F}\mathbf{z}_{k}\right) \\ \sin\left(2\pi\mathbf{F}\mathbf{z}_{k}\right) \end{bmatrix}, \mathbf{F} \sim \mathcal{N}\left(\mathbf{0}_{F}, \sigma_{F}^{2}\mathrm{Id}_{F}\right)$$

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where sim $(\mathbf{h}_i, \mathbf{h}_j)$ is a similarity metric:

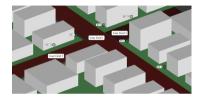
$$\sin\left(\mathbf{h}_{i},\mathbf{h}_{j}\right) = \frac{\left|\mathcal{E}\left(\mathbf{h}_{i}\right)^{\mathsf{H}}\mathcal{E}\left(\mathbf{h}_{j}\right)\right|}{\left\|\mathcal{E}\left(\mathbf{h}_{i}\right)\right\|_{2}\left\|\mathcal{E}\left(\mathbf{h}_{j}\right)\right\|_{2}}.$$

(5)

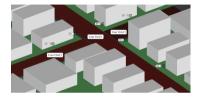
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Two scenes:

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 - DeepMIMO: urban canyon, 3.5GHz

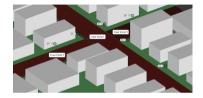


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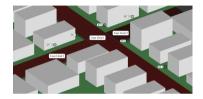


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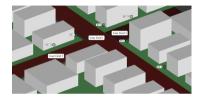


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• Evaluation metrics:

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 - Mono-UE scenario, squared-cosine similarity:

$$\rho_k = \frac{\left|\mathbf{v}_k^{\mathsf{H}}\mathbf{h}_k\right|^2}{\left\|\mathbf{v}_k\right\|_2^2 \left\|\mathbf{h}_k\right\|_2^2}$$

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• Multi-UE scenario, ergodic sum-rate:

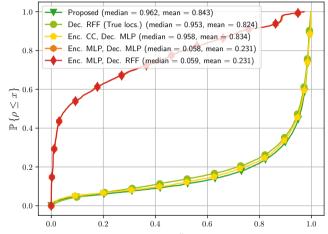
$$\overset{\circ}{\mathcal{R}} = \frac{1}{B} \sum_{b=1}^{B} \sum_{k} \log_2 \left(1 + \frac{\left| \mathbf{h}_{k,b}^{\mathsf{H}} \mathbf{w}_{k,b} \right|^2}{\sigma_{k,b}^2 + \sum_{j \neq k} \left| \mathbf{h}_{k,b}^{\mathsf{H}} \mathbf{w}_{j,b} \right|^2} \right),$$

UE set partition into B groups of K UEs. $\mathbf{W}_b = \mathcal{D}_2 \circ \left(\{ \mathbf{v}_{k,b} \}_{k=1}^K \right)$

(6)

(7)

EXPERIMENTS: PERFORMANCE WRT. BASELINES



x

	Network	a
	Params.	101k
Sionna	Median ρ	0.88
	Mean ρ	0.79
DeepMIMO	Median $ ho$	0.91
	Mean ρ	0.73

• a. No encoder learning, no subsampling

	Network	a	b	
	Params.	$101 \mathrm{k}$	$10.3 \mathrm{M}$	
Sionna	Median ρ	0.88	0.94	
	Mean ρ	0.79	0.86	
DeepMIMO	Median ρ	0.91	0.96	
	Mean ρ	0.73	0.85	

a. No encoder learning, no subsampling

• b. Encoder learning, no subsampling

	Network	a	b	с	
	Params.	$101 \mathrm{k}$	$10.3 \mathrm{M}$	306k	
Sionna	Median ρ	0.88	0.94	0.94	
	Mean ρ	0.79	0.86	0.88	
DeepMIMO	Median $ ho$	0.91	0.96	0.97	
	Mean ρ	0.73	0.85	0.87	

- a. No encoder learning, no subsampling
- c. Encoder learning, subsampling $(\tilde{N} = 100)$

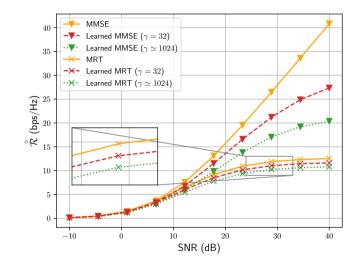
• b. Encoder learning, no subsampling

	Network	a	b	С	d
	Params.	$101 \mathrm{k}$	$10.3 \mathrm{M}$	306k	$121 \mathrm{k}$
Sionna	Median ρ	0.88	0.94	0.94	0.94
	Mean ρ	0.79	0.86	0.88	0.88
DeepMIMO	Median $ ho$	0.91	0.96	0.97	0.96
	Mean ρ	0.73	0.85	0.87	0.84

- a. No encoder learning, no subsampling
- c. Encoder learning, subsampling $(\tilde{N} = 100)$

- b. Encoder learning, no subsampling
- d. Encoder learning, subsampling $(\tilde{N} = 10)$

EXPERIMENTS: MULTI-UE PERFORMANCE



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 - Power allocation policy learning
 - SR-optimization through UE grouping policy learning

THANKS!